

# EXISTENCE OF GLOBAL SOLUTIONS FOR A SYSTEM OF REACTION-DIFFUSION EQUATIONS WITH EXPONENTIAL NONLINEARITY

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**ABSTRACT.** We consider the question of global existence and uniform boundedness of nonnegative solutions of a system of reaction-diffusion equations with exponential nonlinearity using Lyapunov function techniques.

## 1. INTRODUCTION

In this paper we consider the following reaction–diffusion system

$$\frac{\partial u}{\partial t} - a\Delta u = \Pi - f(u, v) - \alpha u \quad (x, t) \in \Omega \times R_+ \quad (1.1)$$

$$\frac{\partial v}{\partial t} - b\Delta v = f(u, v) - \sigma\kappa(v) \quad (x, t) \in \Omega \times R_+ \quad (1.2)$$

with the boundary conditions

$$\frac{\partial u}{\partial \eta} = \frac{\partial v}{\partial \eta} = 0 \quad \text{on } \partial\Omega \times R_+, \quad (1.3)$$

and the initial data

$$u(0, x) = u_0(x) \geq 0; \quad v(0, x) = v_0(x) \geq 0 \quad \text{in } \Omega, \quad (1.4)$$

where  $\Omega$  is a smooth open bounded domain in  $R^n$ , with boundary  $\partial\Omega$  of class  $C^1$  and  $\eta$  is the outer normal to  $\partial\Omega$ . The constants of diffusion  $a, b$  are positive and such that  $a \neq b$  and  $\Pi, \alpha, \sigma$  are positive constants,  $\kappa$  and  $f$  are nonnegative functions of class  $C^1(R_+)$  and  $C^1(R_+ \times R_+)$  respectively.

The reaction-diffusion system (1.1) – (1.4) arises in the study of physical, chemical, and various biological processes including population dynamics (especially AIDS, see C. Castillo-Chavez et al. [3], for further details see [5, 7, 12, 16, 17]).

The case  $\Pi = 0, \alpha = 0, \sigma = 0$  and  $f(u, v) = h(u)T(v)$ , with  $h(u) = u$  (for simplicity), has been studied by many authors. Alikakos [1] established the existence of global solutions when  $T(v) \leq C(1 + |v|^{(n+2)/n})$ . Then Massuda [13] obtained a positive result for the case  $T(v) \leq C(1 + |v|^\alpha)$  with arbitrary  $\alpha > 0$ . The question when  $T(v) = e^{\alpha v^\beta}$ ,  $0 < \beta < 1, \alpha > 0$  was positively answered by Haraux and Youkana [9], using Lyapunov function techniques, see also Barabanova [2] for  $\beta = 1$ , with some conditions and later on by Kanel and Kirane [11], using useful properties inherent to the Green function. The idea behind the Lyapunov functional stems from Zelenyak's article [18], which has also been used by Crandall et al. [4] for other purposes.

The goal of this work is to generalize the existing results of L. Melkemi et al. [14],

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where they established the existence of global solutions, when  $f(\xi, \tau) \leq \psi(\xi)\varphi(\tau)$  such that

$$\lim_{\tau \rightarrow +\infty} \frac{\ln(1 + \varphi(\tau))}{\tau} = 0.$$

Hence, the main purpose of this paper is to give a positive answer, concerning the global existence and the uniform boundedness in time, of solutions of system (1.1) – (1.4), with exponential nonlinearity, such that  $f$  satisfies

- (A1)  $\forall \tau \geq 0, f(0, \tau) = 0,$
- (A2)  $\forall \xi \geq 0, \forall \tau \geq 0, 0 \leq f(\xi, \tau) \leq \varphi(\xi)(\tau + 1)^\lambda e^{r\tau},$
- (A3)  $\kappa(\tau) = \tau^\mu, \mu \geq 1,$

where  $r, \lambda$  are positive constants, such that  $\lambda \geq 1$ ,  $\varphi$  is a nonnegative function of class  $C(R^+)$ .

Our aim in this work, is to establish the global existence of solutions of (1.1) – (1.4), with exponential nonlinearity expressed by the condition (A2), for arbitrary  $v_0$  and  $u_0$  satisfying

$$\max \left( \|u_0\|_\infty, \frac{\Pi}{\alpha} \right) < \frac{\theta^2}{2 - \theta} - \frac{8ab}{rn(a - b)^2}, \quad (1.5)$$

where  $\theta < 1$  is a positive real number very close to 1.

For this end we use comparison principle and Lyapunov function techniques.

## 2. EXISTENCE OF LOCAL SOLUTIONS

The usual norms in spaces  $L^p(\Omega)$ ,  $L^\infty(\Omega)$  and  $C(\overline{\Omega})$  are respectively denoted by

$$\|u\|_p^p = \frac{1}{|\Omega|} \int_\Omega |u(x)|^p dx, \quad \|u\|_\infty = \max_{x \in \Omega} |u(x)|.$$

Concerning a local existence, we can conclude directly from the theory of abstract semilinear equations (see A. Friedman [6], D. Henry [10], A. Pazy [15]), that for nonnegative functions  $u_0$  and  $v_0$  in  $L^\infty(\Omega)$ , there exists a unique local nonnegative solution  $(u, v)$  of system (1.1) – (1.4) in  $C(\overline{\Omega})$  on  $]0, T^*[$ , where  $T^*$  is the eventual blowing-up time.

## 3. EXISTENCE OF GLOBAL SOLUTIONS

Using the comparison principle, one obtains

$$0 \leq u(t, x) \leq \max \left( \|u_0\|_\infty, \frac{\Pi}{\alpha} \right), \quad (3.1)$$

from which it remains to establish the uniform boundedness of  $v$ .

According to the results of [8], it is enough to show that

$$\|f(u, v) - \sigma\kappa(v)\|_p \leq C \quad (3.2)$$

(where  $C$  is a nonnegative constant independent of  $t$ ) for some  $p > \frac{n}{2}$ .

The main result of this paper is

**Theorem 3.1.** *Under the assumptions (A1) – (A3) and (1.5), the solutions of (1.1) – (1.4) are global and uniformly bounded on  $[0, +\infty[$ .*

Let be  $\omega, \beta, \gamma$  and  $M$  positive constants such that  $\omega \geq 1$ ,

$$\beta = \theta \frac{4ab}{(a-b)^2}, \quad \gamma = \max \left( \lambda, \mu, \frac{(\beta+1)(2-\theta)Mr}{\beta\theta(1-\theta)} \right) \quad (3.3)$$

and

$$M = \max \left( \|u_0\|_\infty, \frac{\Pi}{\alpha} \right) < \frac{\theta^2}{2-\theta} \frac{8ab}{rn(a-b)^2}. \quad (3.4)$$

We can choose

$$p = \frac{\theta^2}{2-\theta} \frac{4ab}{(a-b)^2 Mr} \quad (3.5)$$

as consequence of (3.4), we observe that  $p > \frac{n}{2}$ .

The key result needed to prove the theorem 3.1 is the following

**Proposition 3.2.** *Assume that (A1) – (A3) hold and let  $(u, v)$  be a solution of (1.1) – (1.4) on  $]0, T^*[$ , with arbitrary  $v_0$  and  $u_0$  satisfying (1.5). Let*

$$R_\rho(t) = \rho \int_\Omega u dx + \int_\Omega \left( \frac{M}{(2-\theta)M-u} \right)^\beta (v+\omega)^{\gamma p} e^{prv} dx. \quad (3.6)$$

*Then, there exist  $p > n/2$  and positive constants  $s$  and  $\Gamma$  such that*

$$\frac{dR_\rho}{dt} \leq -sR_\rho + \Gamma. \quad (3.7)$$

It's very important to state a number of lemmas, before proving this proposition.

**Lemma 3.3.** *If  $(u, v)$  is a solution of (1.1) – (1.4) then*

$$\int_\Omega f(u, v) dx \leq \Pi |\Omega| - \frac{d}{dt} \int_\Omega u(t, x) dx. \quad (3.8)$$

*Proof.* We integrate both sides of (1.1),

$$f(u, v) = \Pi - \alpha u - \frac{d}{dt} u(t, x) - a \Delta u$$

satisfied by  $u$ , which is positive and then we find (3.8).  $\square$

**Lemma 3.4.** *Let be  $\psi$  a nonnegative function of class  $C(R^+)$ , such that*

$$\lim_{\tau \rightarrow +\infty} \frac{\psi(\tau)}{\tau + \omega} = 0$$

*and let  $A$  be positive constant. Then there exists  $N_1 > 0$ , such that*

$$\left[ \frac{\psi(\tau)}{\tau + \omega} - A \right] (\tau + \omega)^{\gamma p} e^{pr\tau} f(\xi, \tau) \leq N_1 f(\xi, \tau), \quad (3.9)$$

*for all  $0 \leq \xi \leq M$  and  $\tau \geq 0$ .*

*Proof.* Since

$$\lim_{\tau \rightarrow +\infty} \frac{\psi(\tau)}{\tau + \omega} = 0,$$

there exists  $\tau_0 > 0$ , such that for all  $0 \leq \xi \leq K, \tau > \tau_0$ , we have

$$\left[ \frac{\psi(\tau)}{\tau + \omega} - A \right] (\tau + \omega)^{\gamma p} e^{pr\tau} f(\xi, \tau) \leq 0.$$

Now if  $\tau$  is in the compact interval  $[0, \tau_0]$ , then the continuous function

$$\chi(\xi, \tau) = [\psi(\tau)(\tau + \omega)^{\gamma p - 1} - A(\tau + \omega)^{\gamma p}]e^{pr\tau}$$

is bounded.  $\square$

**Lemma 3.5.** *For all  $\tau \geq 0$  we have*

$$\left[ \frac{\Pi\beta}{(1-\theta)M} - \sigma p \kappa(\tau) \left( \frac{\gamma}{\tau + \omega} + r \right) \right] (\tau + \omega)^{\gamma p} e^{pr\tau} \leq -s(\tau + \omega)^{\gamma p} e^{pr\tau} + B_1, \quad (3.10)$$

where  $B_1$  and  $s$  are positive constants.

*Proof.* Let us put

$$\xi = \frac{\Pi\beta}{(1-\theta)M} + s$$

$$\begin{aligned} & \frac{\Pi\beta}{(1-\theta)M} (\tau + \omega)^{p\gamma} e^{pr\tau} - \sigma p \kappa(\tau) [\gamma(\tau + \omega)^{\gamma p - 1} + r(\tau + \omega)^{\gamma p}] e^{pr\tau} = \\ & \left( \frac{\Pi\beta}{(1-\theta)M} - \xi \right) (\tau + \omega)^{p\gamma} e^{pr\tau} + \left( \frac{\xi}{\kappa(\tau)} - \sigma r p \right) \kappa(\tau) (\tau + \omega)^{\gamma p} e^{pr\tau}, \end{aligned}$$

then, using Lemma 3.4 we can conclude the result.  $\square$

*Proof.* (of Proposition 3.2)

Let

$$g(u) = \left( \frac{M}{(2-\theta)M - u} \right)^\beta,$$

so that

$$R_\rho(t) = \rho \int_{\Omega} u dx + G(t),$$

where

$$G(t) = \int_{\Omega} g(u)(v + \omega)^{\gamma p} e^{prv} dx.$$

Differentiating  $G$  with respect to  $t$  and a simple use of Green's formula gives

$$G'(t) = I + J,$$

where

$$\begin{aligned} I = & -a \int_{\Omega} g''(u)(v + \omega)^{\gamma p} e^{prv} |\nabla u|^2 dx \\ & - (a + b) \int_{\Omega} g'(u) [\gamma p(v + \omega)^{\gamma p - 1} + pr(v + \omega)^{\gamma p}] e^{prv} \nabla u \nabla v dx \\ & - b \int_{\Omega} g(u) [\gamma p(\gamma p - 1)(v + \omega)^{\gamma p - 2} + 2\gamma p^2 r(v + \omega)^{\gamma p - 1} + p^2 r^2 (v + \omega)^{\gamma p}] e^{prv} |\nabla v|^2 dx, \\ J = & \int_{\Omega} \Pi g'(u)(v + \omega)^{\gamma p} e^{prv} dx - \int_{\Omega} \alpha g'(u) u (v + \omega)^{\gamma p} e^{prv} dx \\ & + \int_{\Omega} \left( g(u) [\gamma p(v + \omega)^{\gamma p - 1} + rp(v + \omega)^{\gamma p}] - g'(u)(v + \omega)^{\gamma p} \right) f(u, v) e^{prv} dx \\ & - \int_{\Omega} \sigma [\gamma p(v + \omega)^{\gamma p - 1} + rp(v + \omega)^{\gamma p}] \kappa(v) g(u) e^{prv} dx. \end{aligned}$$

We can see that  $I$  involves a quadratic form with respect to  $\nabla u$  and  $\nabla v$ , which is nonnegative if

$$\begin{aligned}\delta = & \left( p(a+b)g'(u)[\gamma(v+\omega)^{\gamma p-1} + r(v+\omega)^{\gamma p}] \right)^2 \\ & - 4ab\gamma p(\gamma p-1)g''(u)g(u)(v+\omega)^{2\gamma p-2} \\ & - 4abg''(u)g(u)(v+\omega)^{\gamma p}[2\gamma p^2 r(v+\omega)^{\gamma p-1} + p^2 r^2(v+\omega)^{\gamma p}] \leq 0.\end{aligned}$$

Indeed

$$\begin{aligned}\delta = & [(p\gamma)^2(a+b)^2\beta^2 - 4ab\beta(\beta+1)p\gamma(p\gamma-1)] \frac{g(u)^2(v+\omega)^{2p\gamma-2}}{((2-\theta)M-u)^2} \\ & + [(a+b)^2\beta^2 - 4ab\beta(\beta+1)] \frac{rp^2g(u)^2(v+\omega)^{2p\gamma-1}}{((2-\theta)M-u)^2} [2\gamma + r(v+\omega)],\end{aligned}$$

the choice of  $\beta$  and  $\gamma$  gives

$$\begin{aligned}\delta \leq & [\beta+1-p\gamma(1-\theta)] \frac{4ab\beta p\gamma g(u)^2(v+\omega)^{2p\gamma-2}}{((2-\theta)M-u)^2} \\ & + 4ab(\theta-1) \frac{rp\beta g(u)^2(v+\omega)^{2p\gamma-1}}{((2-\theta)M-u)^2} [2 + (rp)(v+\omega)] \leq 0,\end{aligned}$$

it follows that

$$I \leq 0.$$

Concerning the second term  $J$ , we can observe that

$$\begin{aligned}J \leq & \int_{\Omega} \left( \frac{\Pi\beta}{(1-\theta)M} - \sigma p\kappa(v) \left[ \frac{\gamma}{v+\omega} + r \right] \right) g(u)(v+\omega)^{p\gamma} e^{prv} dx \\ & + \int_{\Omega} \left( p \left[ \frac{\gamma}{v+\omega} + r \right] - \frac{\beta}{(2-\theta)M-u} \right) f(u,v)g(u)(v+\omega)^{\gamma p} e^{prv} dx.\end{aligned}$$

Using Lemma 3.5, we get

$$\begin{aligned}J \leq & \int_{\Omega} [-s(v+\omega)^{p\gamma} e^{prv} + B_1]g(u)dx \\ & + \int_{\Omega} \left( p \left[ \frac{\gamma}{v+\omega} + r \right] - \frac{\theta}{2-\theta} \frac{4ab}{(a-b)^2 M} \right) f(u,v)g(u)(v+\omega)^{\gamma p} e^{prv} dx,\end{aligned}$$

or

$$\begin{aligned}J \leq & \int_{\Omega} [-s(v+\omega)^{p\gamma} e^{prv} + B_1]g(u)dx \\ & + \int_{\Omega} \left( \frac{p\gamma}{v+\omega} - \frac{\theta(1-\theta)}{2-\theta} \frac{4ab}{(a-b)^2 M} \right) f(u,v)g(u)(v+\omega)^{\gamma p} e^{prv} dx \\ & + \int_{\Omega} \left( pr - \frac{\theta^2}{2-\theta} \frac{4ab}{(a-b)^2 M} \right) f(u,v)g(u)(v+\omega)^{\gamma p} e^{prv} dx.\end{aligned}$$

From Lemma 3.4 and formula (3.5), it follows

$$\begin{aligned}J \leq & \int_{\Omega} [-s(v+\omega)^{p\gamma} e^{prv} + B_1]g(u)dx \\ & + N_1 \int_{\Omega} f(u,v)g(u)dx.\end{aligned}$$

In addition

$$g(u) \leq \left( \frac{1}{1-\theta} \right)^\beta,$$

then

$$J \leq -sG(t) + |\Omega| B_1 \left( \frac{1}{1-\theta} \right)^\beta + N_1 \left( \frac{1}{1-\theta} \right)^\beta \int_{\Omega} f(u, v) dx.$$

Then if we put

$$B = B_1 |\Omega| \left( \frac{1}{1-\theta} \right)^\beta$$

and

$$\rho = N_1 \left( \frac{1}{1-\theta} \right)^\beta.$$

Then, if we use Lemma 3.3,

$$\begin{aligned} J &\leq -sR_\rho(t) + s\rho \int_{\Omega} u(t, x) dx + B + \rho \Pi |\Omega| - \rho \frac{d}{dt} \int_{\Omega} u(t, x) dx \\ &\leq -sR_\rho(t) + [sM + \Pi]\rho |\Omega| + B - \rho \frac{d}{dt} \int_{\Omega} u(t, x) dx, \end{aligned}$$

it follows that

$$\frac{dR_\rho}{dt} \leq -sR_\rho + \Gamma,$$

where  $\Gamma = [sM + \Pi]\rho |\Omega| + B$ . □

*Proof.* (of Theorem 3.1)

Multiplying (3.7) by  $e^{st}$  and integrating the inequality, it implies the existence of a positive constant  $C > 0$  independent of  $t$  such that

$$R_\rho(t) \leq C.$$

Since

$$\begin{aligned} g(u) &\geq \left( \frac{1}{2-\theta} \right)^\beta, \\ \int_{\Omega} (v + \omega)^{\gamma p} e^{prv} dx &\leq (2-\theta)^\beta R_\rho(t) \\ &\leq C(2-\theta)^\beta. \end{aligned}$$

Since  $\omega \geq 1$  and (3.3) we have also,

$$\begin{aligned} \int_{\Omega} (v + 1)^{\lambda p} e^{prv} dx &\leq \int_{\Omega} (v + \omega)^{\gamma p} e^{prv} dx \leq C(2-\theta)^\beta, \\ \int_{\Omega} v^{\mu p} dx &\leq \int_{\Omega} (v + \omega)^{\gamma p} dx \leq C(2-\theta)^\beta. \end{aligned}$$

We put

$$A = \max_{0 \leq \xi \leq M} \varphi(\xi),$$

according to (A1) – (A3), we have

$$\int_{\Omega} f(u, v)^p dx \leq \int_{\Omega} A^p (v + 1)^{\lambda p} e^{prv} dx \leq A^p C(2-\theta)^\beta = A^p H^p,$$

we conclude

$$\|f(u, v) - \sigma\kappa(v)\|_p \leq \|f(u, v)\|_p + \|\sigma\kappa(v)\|_p \leq H(A + \sigma).$$

By the preliminary remarks (introduction of section 3), we conclude that the solution of (1.1) – (1.4) is global and uniformly bounded on  $[0, +\infty[\times\Omega$ .

□

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